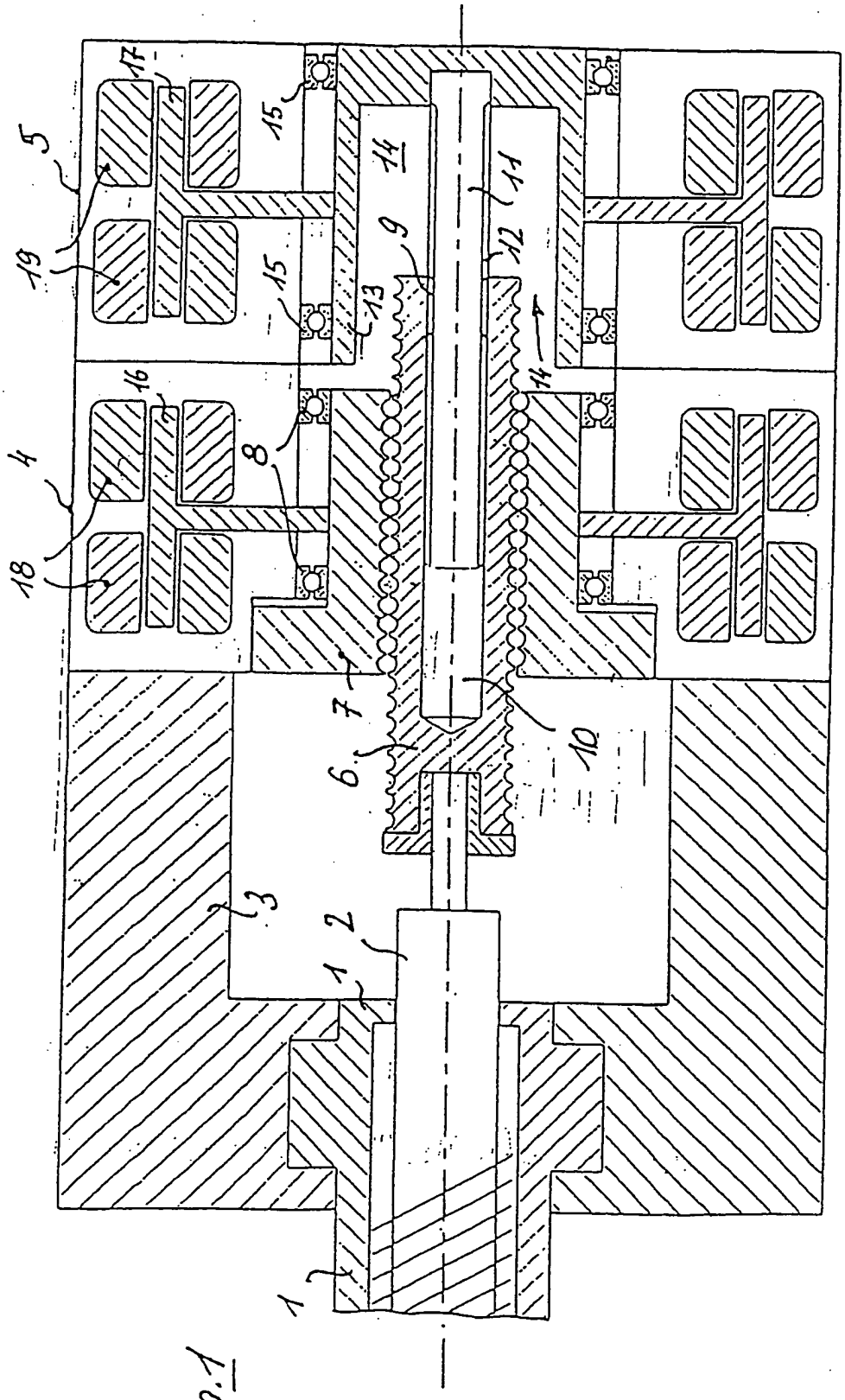
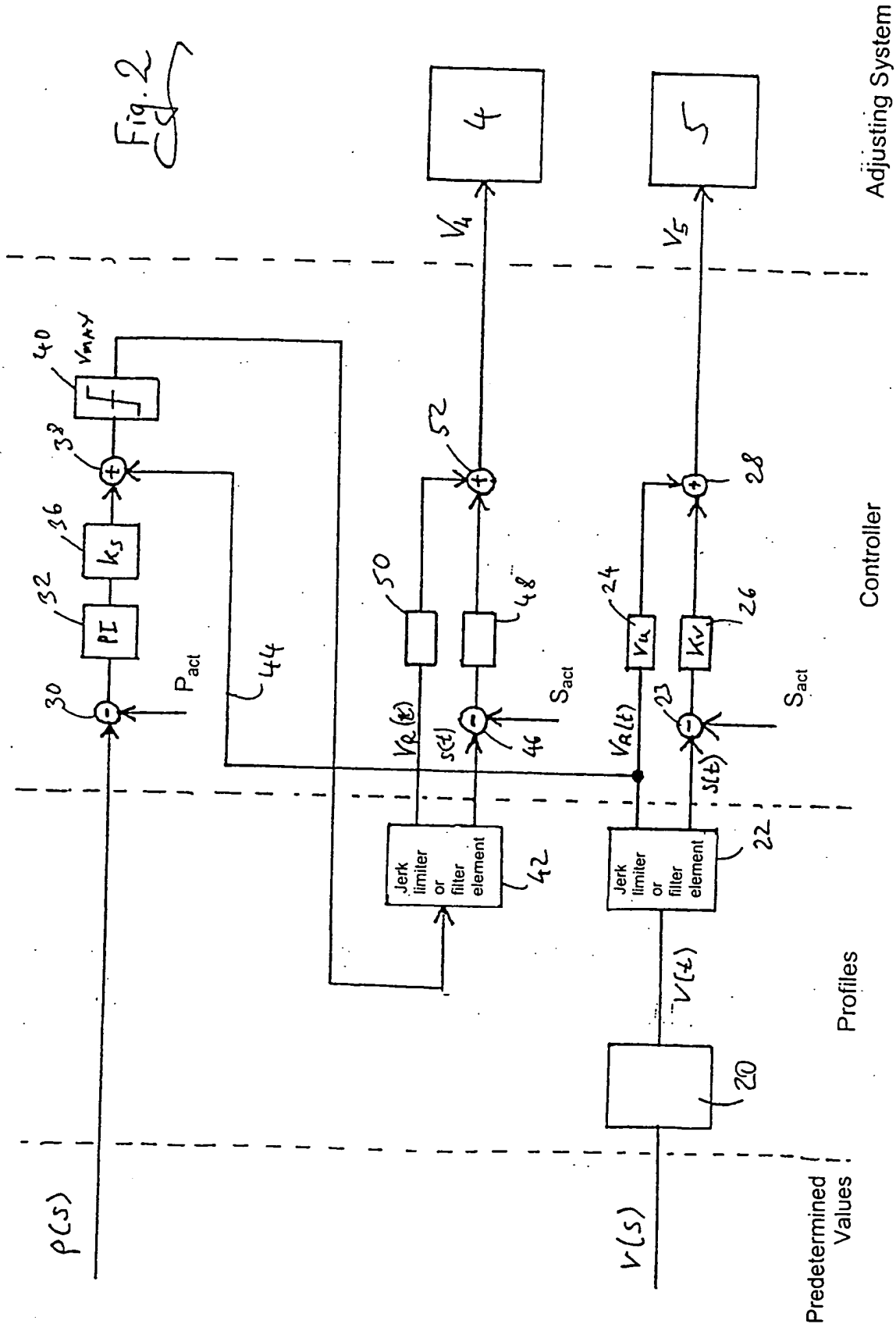


Fig.1

Fig. 2


Predetermined Values
Profiles
Controller
Adjusting System
P(s)
V(s)
V(t)
20
Jerk limiter or filter element
42
Jerk limiter or filter element
22
PI
32
k_s
36
30
38
40
v_{max}
P_{act}
44
$V_R(t)$
s(t)
46
S_{act}
48
50
52
V_4
4
$V_A(t)$
s(t)
23
S_{act}
24
V_A
k_v
26
28
V_5
5